



COMPLETE METALWORKING SOLUTIONS
(800) 991-4225 www.ahbinc.com
ISO Certified customerservice@ahbinc.com

MELTIO

Meltio Engine CNC Hybrid Process



Meltio Engine CNC Integration

Hybrid Manufacturing Integration

The most affordable hybrid manufacturing solution, fitting almost any CNC machine in the market. Enable metal 3D printing and machining of complex geometries in a single process step.

Hybrid Manufacturing

Create highly complex parts with machining tolerances in the same process.

Part Repair

Cost-effective component repair, part augmentation and feature addition.

Retrofitting

Provide new capability to any CNC machine by turning it into a hybrid metal manufacturing system.

Geometry Freedom

No inherent constraints when the working envelope is only limited by the size of the motion system.



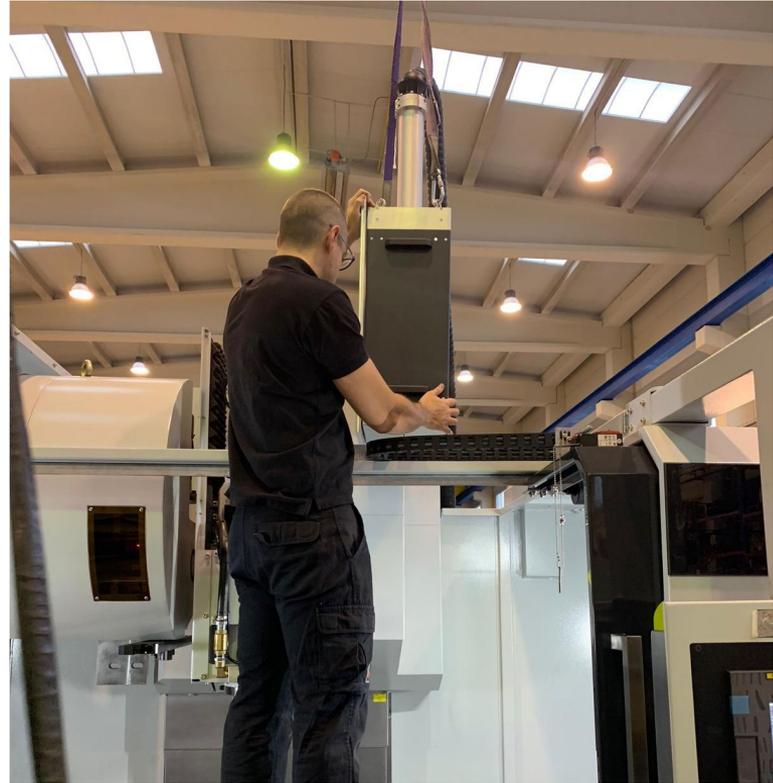
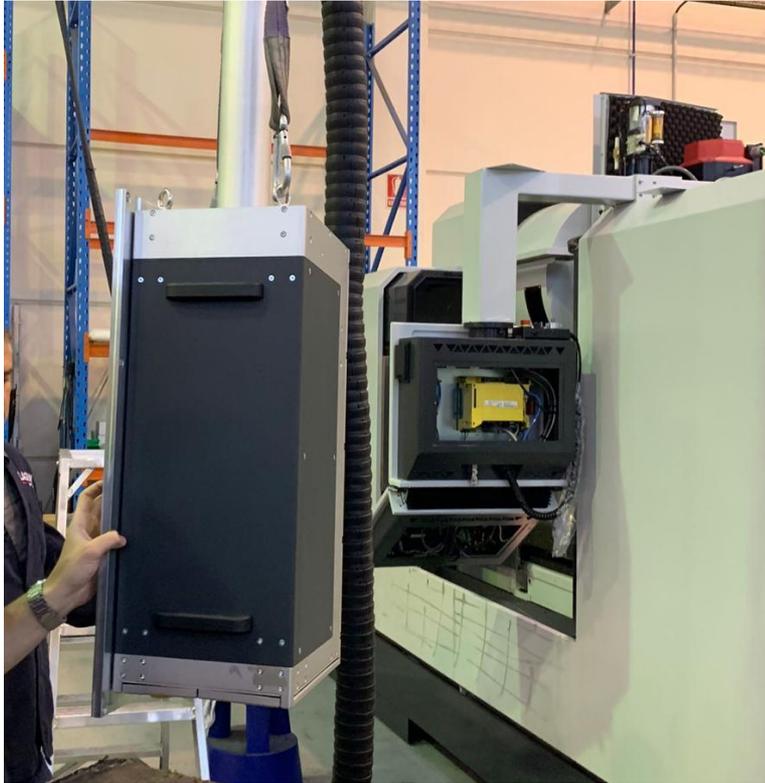
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Bolt-on Hardware Integration



Adapter Plate



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Minimum requirements:

-Hybrid integration: Hardware + Safety + Mcodes

-Hybrid CAM software: (Example: Mastercam + Aplus)

-Specific training (CNC, hybrid product, Meltio).

Hybrid CAM Software:

Meltio Open platform

Meltio Software Partners Ecosystem for the Hybrid process

Examples of CNC hybrid software are:
MasterCam + Aplus Additive plugin, Esprit by Hexagon; Fusion 360 or PowerMill by Autodesk; Hypermill by OpenMind; SiemensNX by Siemens; Hy5CAM by 1ATechnologies; and SprutCAM X by SprutCam.





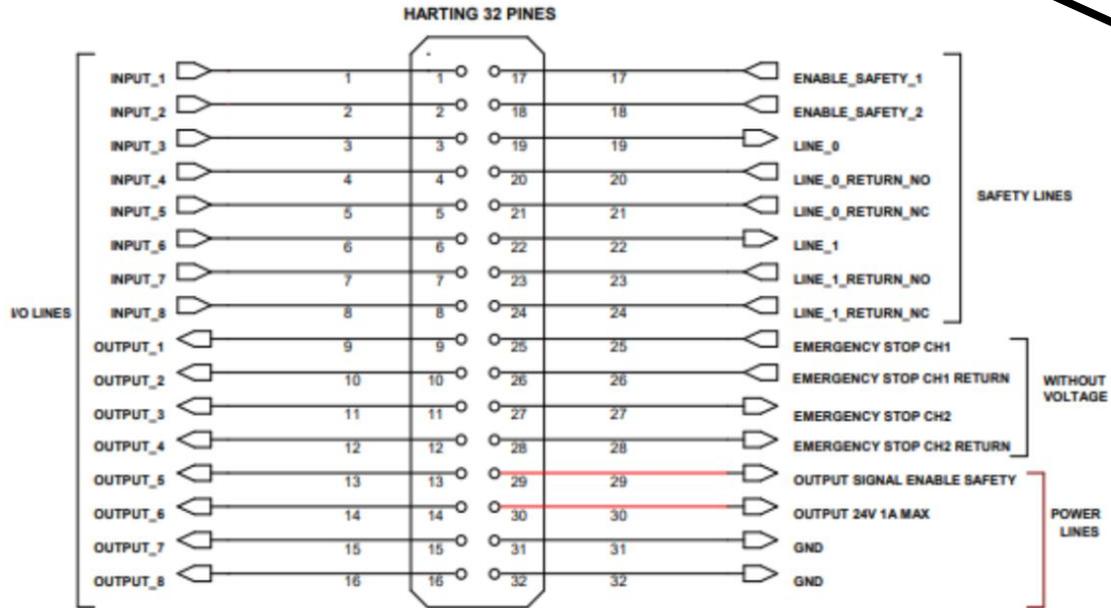
CNC / Hybrid integrations: How does the integration work

- Gcode goes in → then to machine → machine talks to engine → Engine supplies process information → then to part
- How does info flow
- Which Information is passed
- How is the information shared

Interfaces and easy integration



I/O & Safety Cable



Pins 1 to 16: I/O communication (32p harting pinout attached).

Pin 17 and 18: 24V constant signal sent from the CNC in case of no emergency (Channel 1 and 2). These 24V must fall in case of door opening.

Pin 19 and 22 (Channel 1 and 2): 24V constant signal from the CNC to our Engine (Input to safety relays controlled by the Engine electronics)

Pin 20 NO or 21 NC for channel 1 return

Pin 23 NO or 24 NC for channel 2 return

The NC and NO state for the Engine's safety relay refer to the relay in an unpowered state. Therefore NC for a red state and NO for a blue state.

Pins 25 and 26: voltage free contact 1 without passing through the electronics (physical emergency stop button of the Engine)

Pins 27 and 28: voltage free contact 2 without passing through the electronics (physical emergency stop button of the Engine)

Pin 29 and 30 - 24V power supply of the engine with active safety (up to 1A) Meltio provides 24V if there is no emergency on ENGINE, e.g. to switch on peripherals such as cameras only when the Engine is ready.

Pin 31 and 32 -GND: 24V common from Meltio

Macros/Mcodes

M104-Initialize Print: Initialize the Meltio Engine for printing, including security checks as well as turning on the chiller and the defined argon flow.

M105- Finalize Printing Process - Reset Signals: Set every Digital Output to low(0) at the beginning of the program to ensure a clear communication and finished the printing process.

M106-Start Deposition: Begins the extrusion of the filament and turns on the lasers.

M107-Start Deposition 2: Allow you to have different Laser Power and Wire Feeder Speed

M108-End Deposition: Ends the extrusion of the filament and turns off the lasers.

M109-Change to T0: Begins the change of material, retract the ACTIVE material 60 mm and extrude T0 material 60 mm.

M110-Change to T1: Begins the change of material, retract the ACTIVE material 60 mm and extrude T1 material 60 mm.

M111-Deploy: Extends the CNC Hardware integration and continues the argon flow.

M112-Enclose: Enclose the CNC Integration Hardware for a Hybrid process. When is enclosed it will stop the use of argon, this allow the Engine to have only one print log for the Hybrid process.

Communication Protocol

Default Communication is based as **Digital I/O**:

Any digital input or output can be assigned, including same output for all confirmations if necessary **just selecting from the list**.

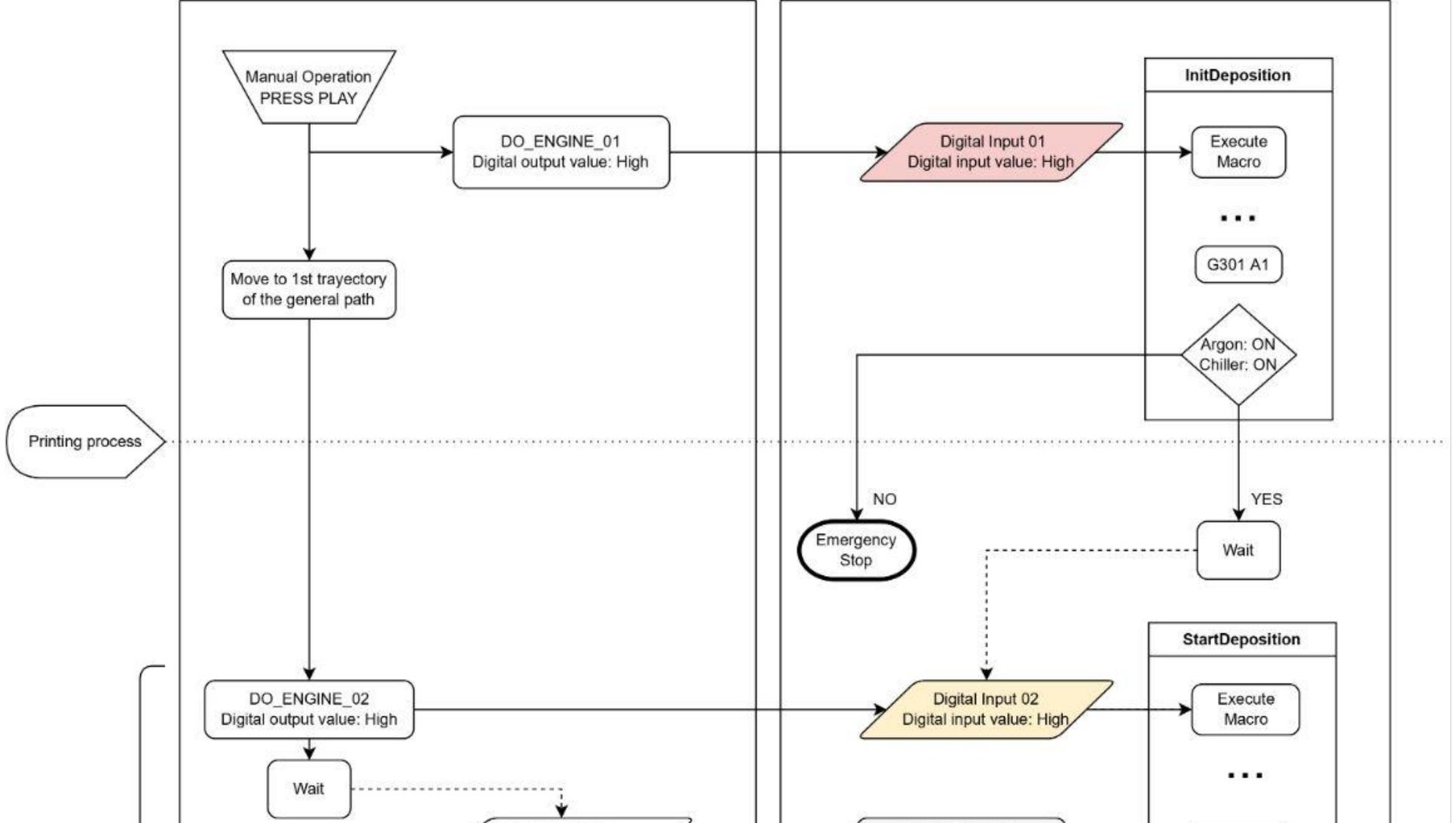
On **CNC Integration Hardware**, includes the option to **enclose and extend** the deployment calling for a signal too.

Exist the possibility to add a delay, by default this is set to 0.

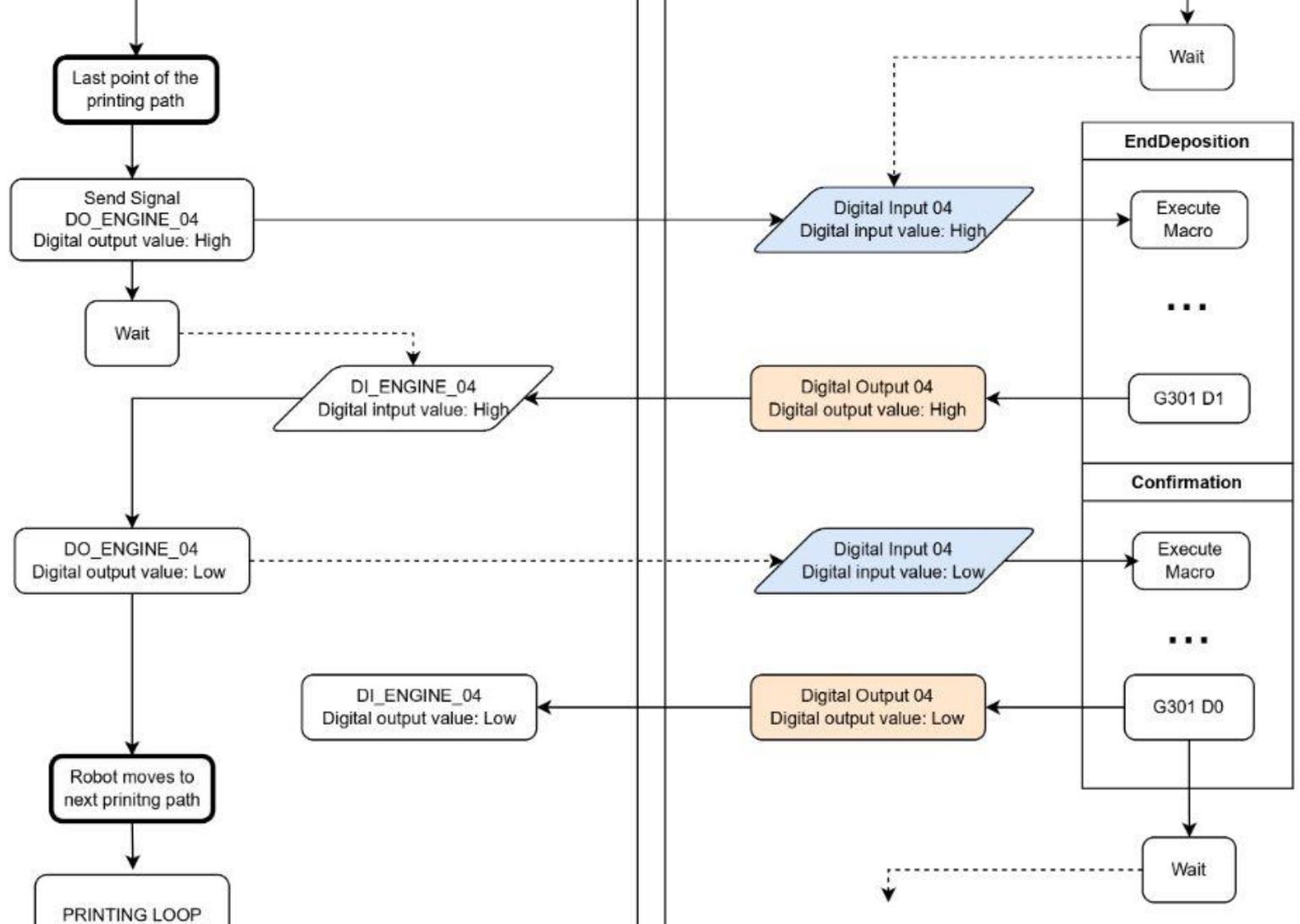
OPC DA and Socket, also available with logic as in previous versions.

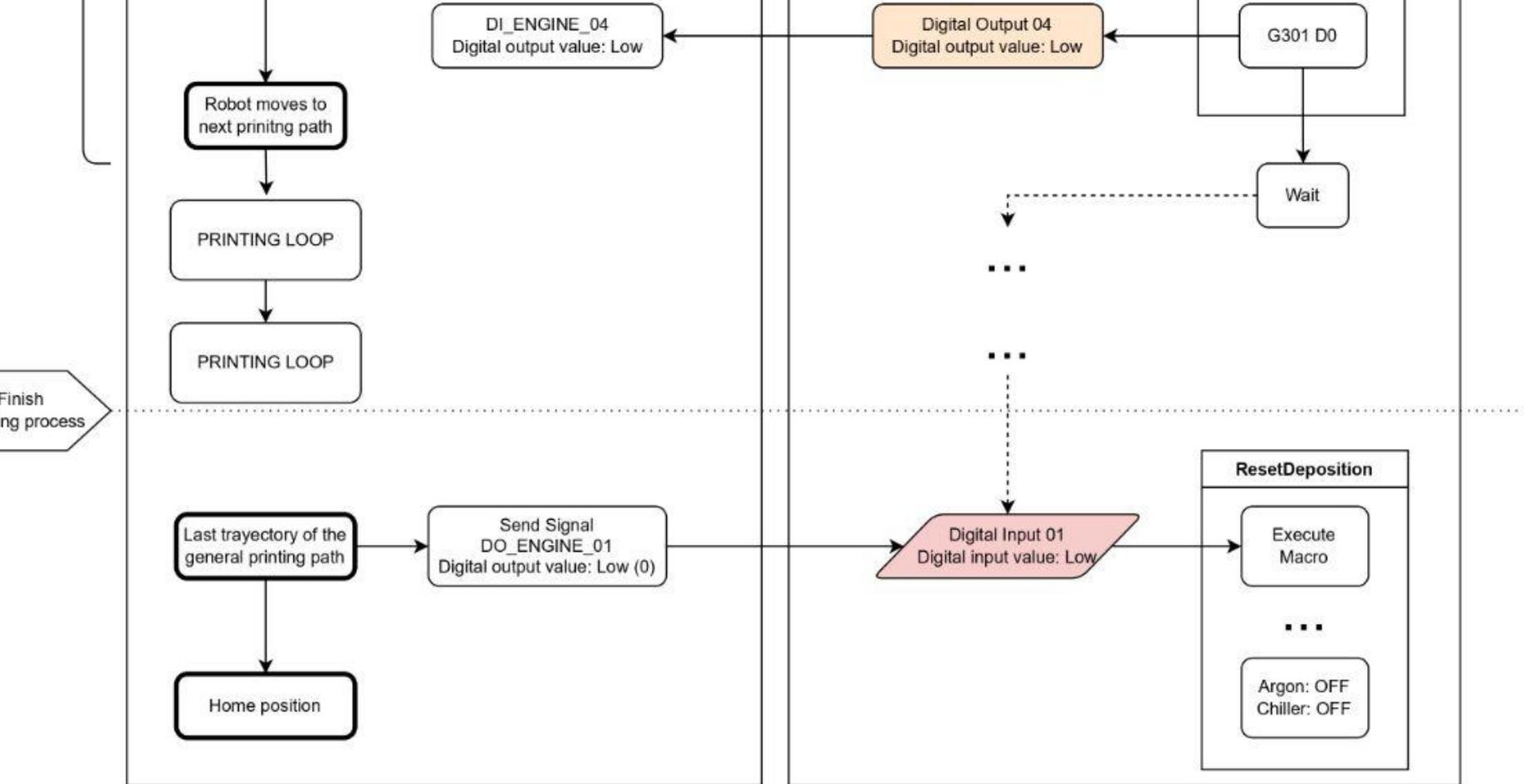
The screenshot shows the 'Communication Protocol' configuration window. At the top, the 'Protocol' is set to 'Digital I/O'. Below this, there are two main sections: 'Launch' and 'Confirmation'. The 'Launch' section has four rows with dropdown menus: 'Initialize Print' (Digital input 01), 'Start Deposition 1' (Digital input 02), 'Start Deposition 2' (None), and 'Start Deposition 3' (None). The 'Confirmation' section has four rows with dropdown menus: 'End Deposition' (Digital output 04), 'Change to T0' (Digital output 05), and 'Change to T1' (Digital output 06). To the right of the 'Confirmation' section, there are two columns for 'Event Delay', each with 'Before' and 'After' fields set to '0' ms. At the bottom right, there are 'Apply' and 'Cancel' buttons.

	Launch	Confirmation	Event Delay	
Initialize Print	Digital input 01			
Start Deposition 1	Digital input 02			
Start Deposition 2	None	Digital output 02	Before 0 ms	After 0 ms
Start Deposition 3	None			
End Deposition	Digital input 04	Digital output 04	Before 0 ms	After 0 ms
Change to T0	Digital input 05	Digital output 05		
Change to T1	Digital input 06	Digital output 06		



PRINTING LOOP

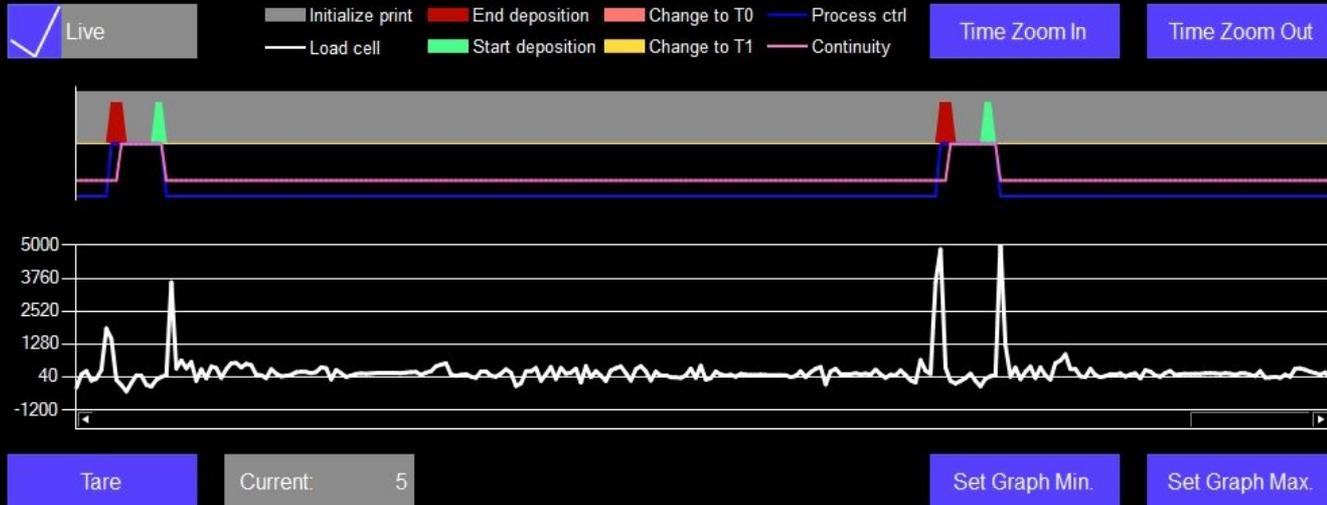




Timeline

Understand more about the Meltio process following everything that occurs in the same Timeline. It includes Macros launch and duration, as well as sensors as the continuity within the Integration Hardware and the part as being printed together with the Load Cell.

Timeline



G00 G17 G21 G40 G80 G90
G91 G28 Z0.

N1

T0 M06 (Tool Change)

T4

G54 G17 G90

M105 (FINALIZE MELTIO ENGINE - RESET SIGNALS)

M104 (INITIALIZE MELTIO ENGINE)

M111 (DEPLOY MELTIO ENGINE)

G04 X15

M109 (MELTIO TO MATERIAL)

G00 X1.276 Y-48.472

G43 H120 Z3.

Z0.

M106 (START DEPOSITION)

G94 G01 X1.266 F600.

X-1.039 Y-48.489

X-3.805 Y-48.35

X-6.559 Y-48.054

X-43.37 Y-21.709

X-44.538 Y-19.198

X-45.562 Y-16.624

...

X27.09 Y-39.017

X24.818 Y-40.5

X4.403 Y-47.295

X2.159 Y-47.439

X2.149 Y-47.44

M108 (END DEPOSITION)

Printing
Loop

...

G00 Z23.4

G49

G91 G28 Z0.

G28 X0. Y0.

M01 (Conditional Program Stop)

N2

M112 (ENCLOSE MELTIO HEAD)

T4 M06 (63 ENDMILL)

T10

G54 G17 G90

G00 X-103.727 Y48.14 S632 M03

G43 H4 Z46.

Z31.

G94 G01 Z20.813 F600.

X103.727 F758.4

...

G01 Z20.813 F600.

X116.804 F758.4

X103.727 Y-48.14

X-103.727

G01 X33.5

G00 Z46.

G49

M09 (End Water and Air Cooling (CNC))

M05 (Spindle Stop)

G91 G28 Z0.

G28 X0. Y0.

M105 (FINALIZE MELTIO ENGINE - RESET SIGNALS)

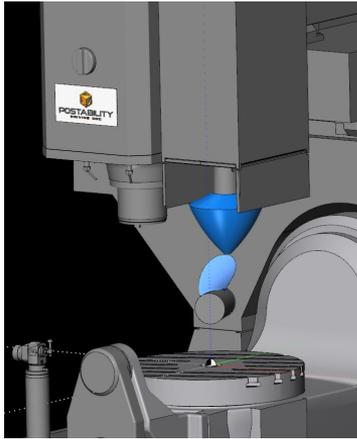
M30

%

Milling

Hybrid Manufacturing process flow

Hybrid manufacturing processes seek to combine the strengths of additive manufacturing (3D printing) with those of traditional CNC Milling / Subtractive manufacturing, to create a single manufacturing workflow that effectively uses both at once.



1. Hybrid Toolpath

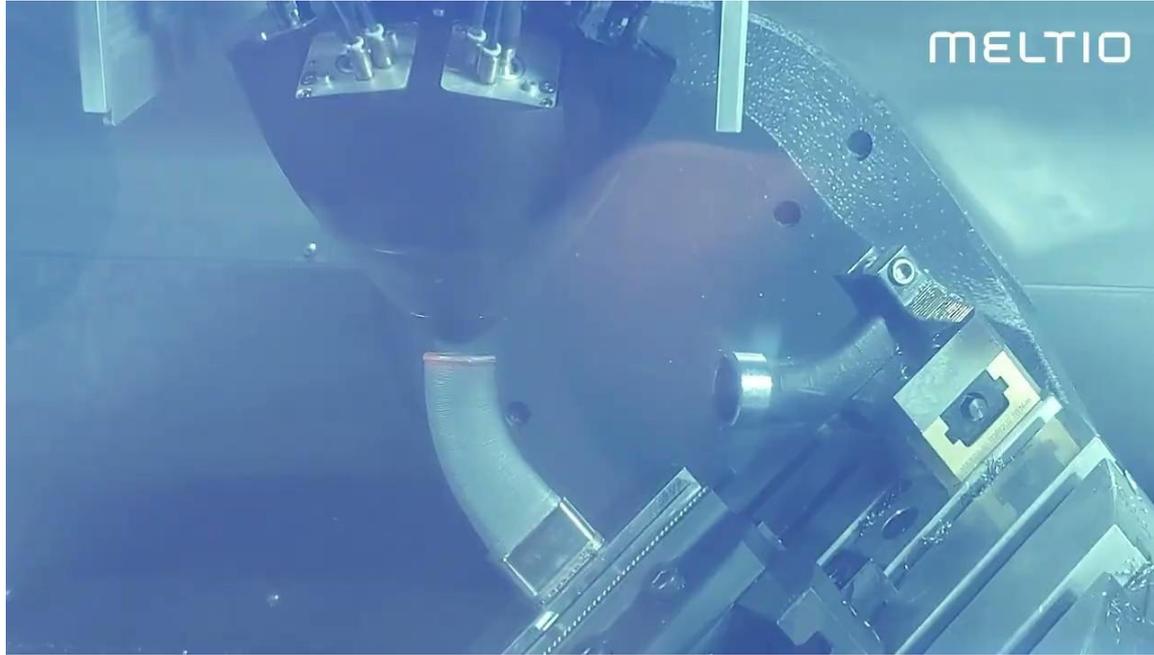


2. Metal 3D Printing



3. CNC Machining

Hybrid Manufacturing of Complex Parts



Machine Setup

- Mechanical Integration (Adapter Plate), Laser Safe Windows, Safety Relays, External Feeders
- Safety Integration (Engine and CNC Controller)
- Communication Integration (Engine and CNC controller / Mcodes)
- Engine Tool Offset / G54-G55 / Tool Corrector

CAM Setup

- Define CNC Hybrid Machine on CAM
- work volume and axis limits
- Post Processor (MCodes) in the controller language. (HAAS, Fanuc, Heidenhein)
- 3D machine simulation including Meltio process head, collision check.

Engine Setup

- Communication Protocol
- Safety Circuit Check

Daily Printing Process



Machine Setup

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Define Meltio Head Height

- Use an exact height tool (pattern)
- Setting the machine coordinates with the pattern
- Measure the height of the Meltio Head
- Defined height in macro windows

Define Meltio Head Distance

- Print a square of 50 x 50 x 30 mm at the G54 origin.
- Use the part measuring probe to find the center of the part at G55.
- Set X0 and Y0 at G55, with different values at G54.
- Calculate the measurement differences between G54 and G55 to determine the X and Y displacements of the Meltio head.
- Define the displacement values in macros, using negative values from G54.

Hybrid Process

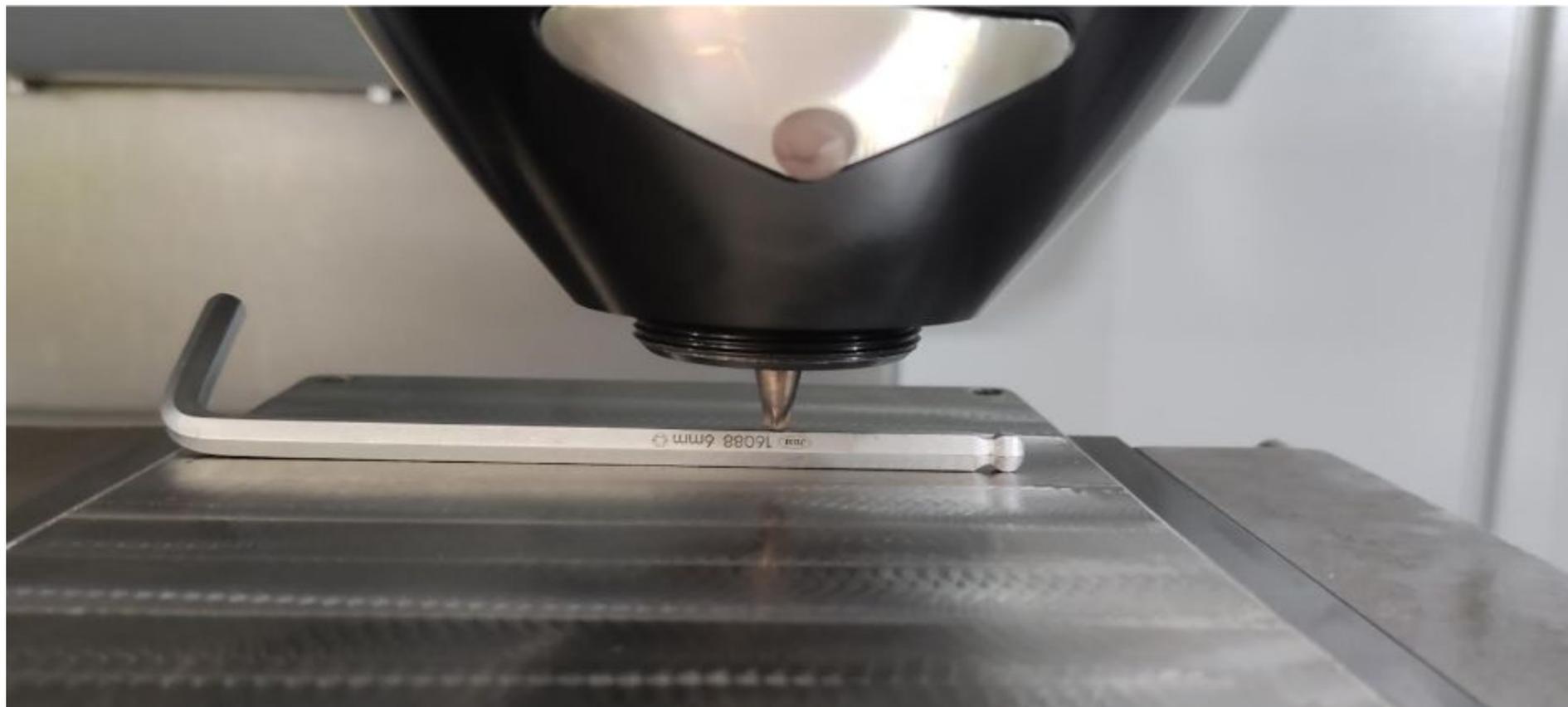
- Set the machining origin in G55.
- Modify values in G54 using the Meltio window.
- Define the zero point in G55
- Define the value in G55 with the distance difference in G54 for all axes.
- Define the corrector H120.
- Ensure Meltio is defined as T0 in the code.

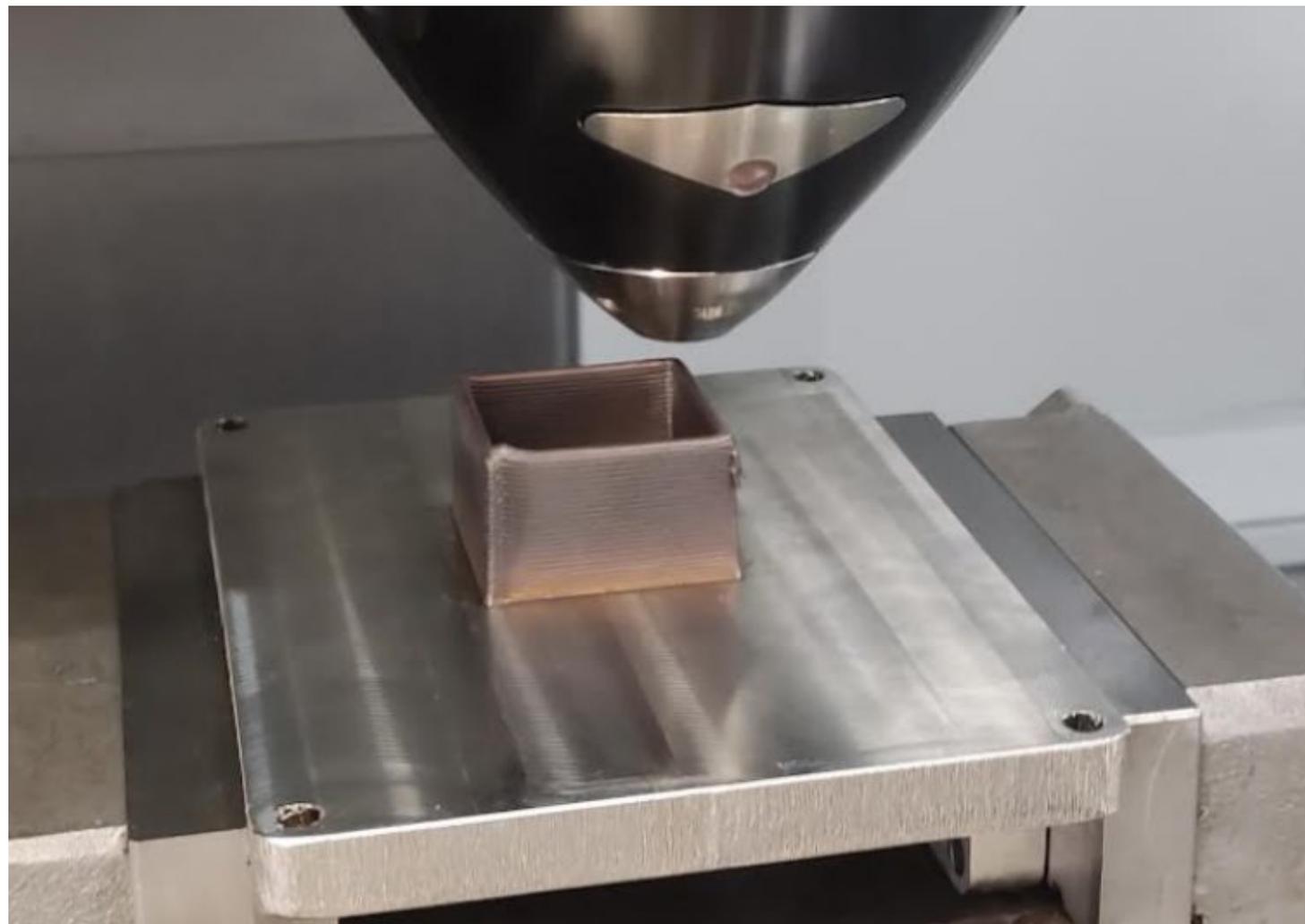


Programming Process

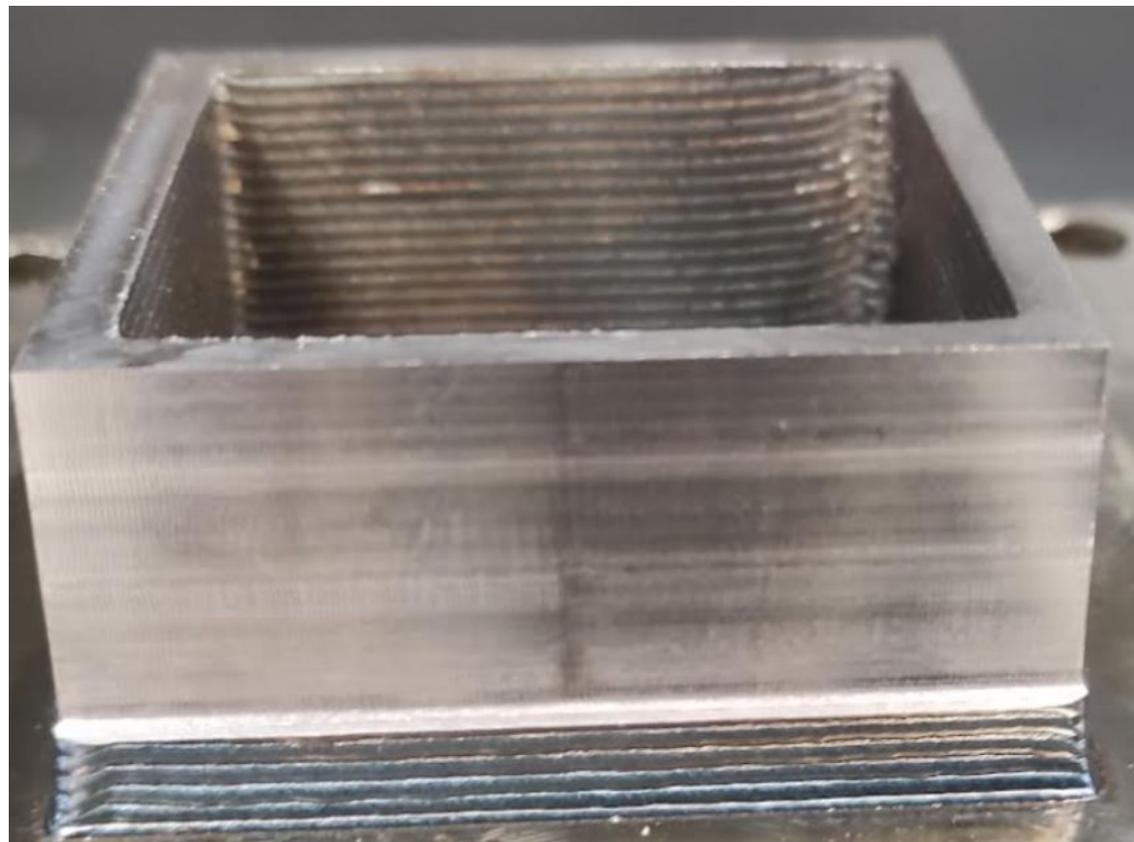
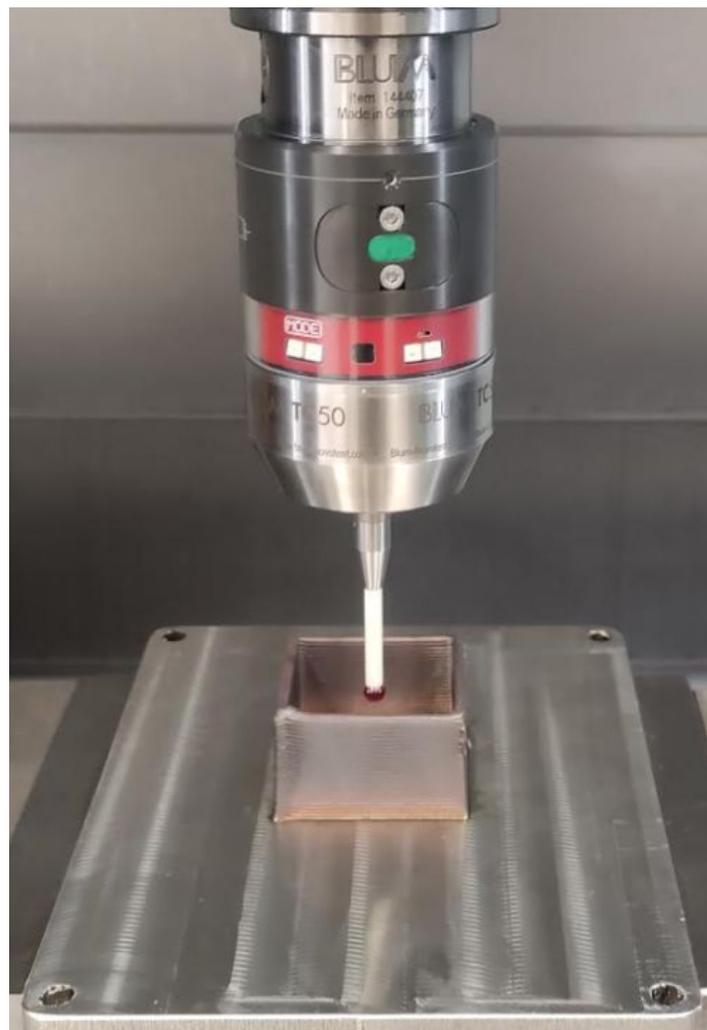
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**More details of machine setup as performed
on Lagun L1600 Powered by Meltio with
FANUC 0imf-Plus controller**

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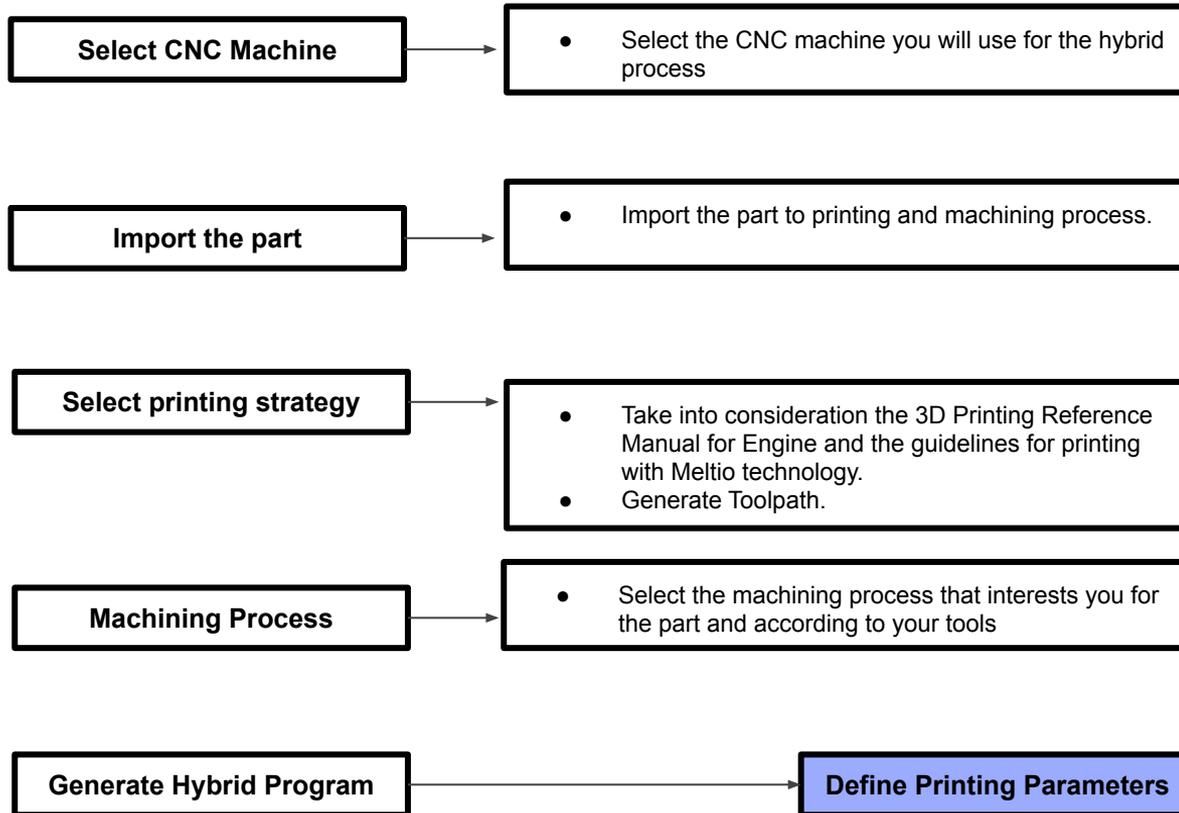
Meltio Engine V3 Integration Manual

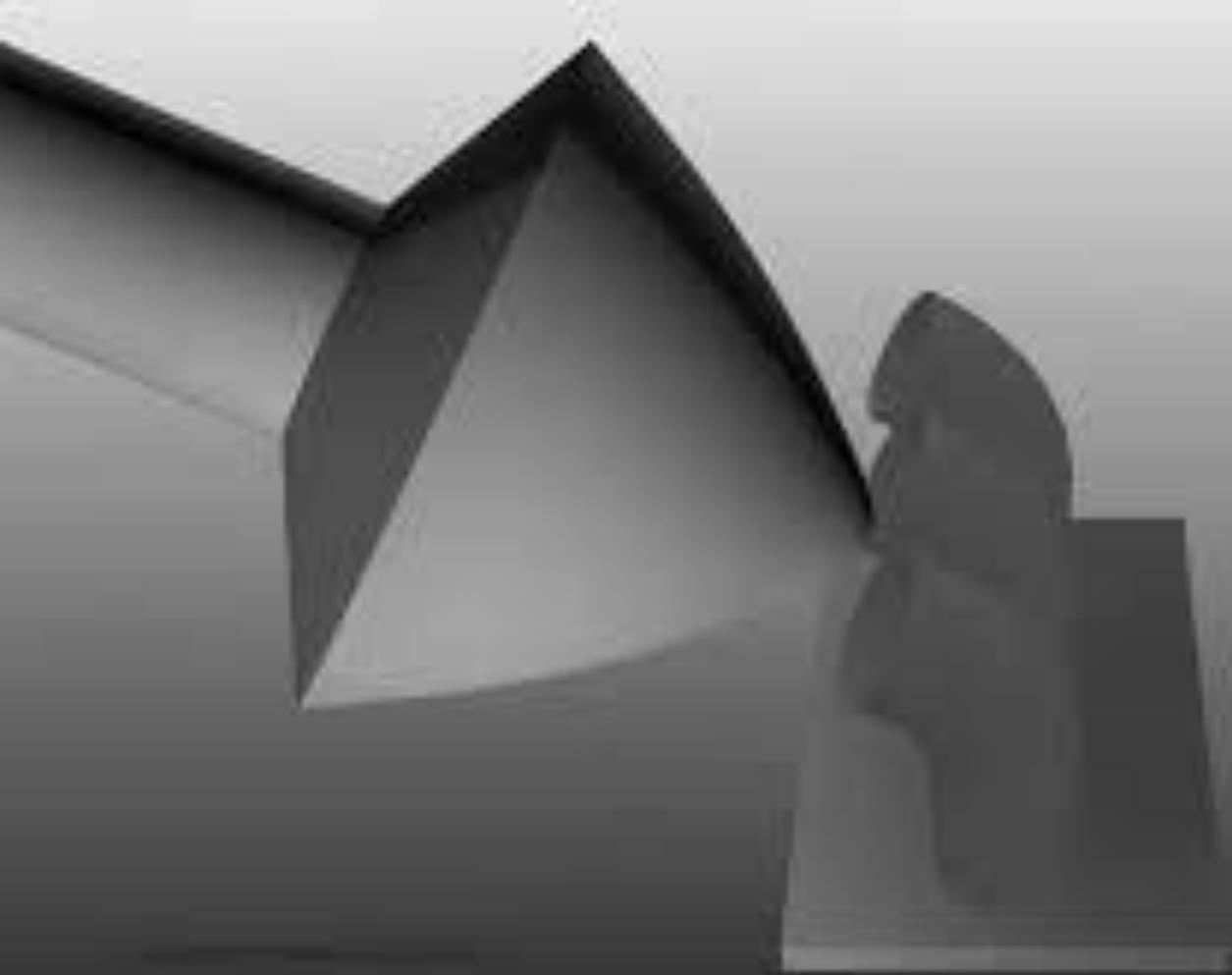
Applies to Meltio Engine - V3 February 2024



CAM Setup

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Engine Setup

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Check Communications Protocols

- Define communication protocol
- In case to use the Digital I/O protocol you must check if the DI launch match with the correct confirmation DO

Select Engine Printing Profile

- Define Power Laser
- Define Feeder Speed
- Define Gas Flow
- In case to use the predefined profiles you must select if your part is solid (Fully Density/ Utility) or hollow (1P, 2P, +3P)

Check Adjust Seam

- Define adjust seam for single wire
- Define adjust seam for dual wire

PRINTING!



Feeder Speed Calculator

We included a very helpful tool to ensure the feeder speed is calculated correctly in case you are using a Custom Print Profile.

Defining the Print Speed (movement), Layer height and Layer width, together with the material wire radius (important to define it in the profile editor) will calculate the Feeder Speed, to be used in any Option for printing.

See the example to obtain 15.28mm/s as the speed of the wire for a 10mm/s robot movement speed, 1.2 mm layer height, and 1mm layer width. Using 1mm wire, hence 0.5 its radius.

Feeder Speed Calculator

Option 1 Option 2 Option 3

mm/s × mm × mm

$$\frac{\text{Print speed} \times \text{Layer height} \times \text{Layer width}}{\pi \times 0.50^2 \text{ mm}} = \text{Feeder speed mm/s}$$

Apply Cancel

Feeder Speed Calculator

Option 1 Option 2 Option 3

mm/s × mm × mm

$$\frac{10.00 \times 1.20 \times 1.00}{\pi \times 0.50^2 \text{ mm}} = 15.28 \text{ mm/s}$$

Apply Cancel

Profile Editor

New interface offers every option parametrized, being able to apply different profile to Tool 0 and Tool 1.

It includes Option 2 and Option 3, to allow, with the same profile to have different Laser, Feeder and Hotwire values, to be applied for Infill, perimeters or even to apply preheating. To be called with extra inputs and outputs.

Cooldown allow you to include extra wait times for part cooldown if necessary.

We offered also sub menus to define easily the best parameters match.

Profile

1st Material (T0) - ACTIVE **Set**

Space Profile Custom Profile

Solid FullDensity 17-4PH

2nd Material (T1)

Space Profile Custom Profile

Select infill

Profile Editor

Solid-FullDensity-17-4PH

Feeder T0

Laser	Feeder	Hotwire	Material	Ø Wire	Gas flow
1024 W	9.55 mm/s	0	17-4PH	1.00 mm	10000 ml/min
Option 2			Process ctrl		
0 W	0.00 mm/s	0	<input checked="" type="checkbox"/> Enabled	Material Library	Comm. Protocol
Option 3			Cooldown		
0 W	0.00 mm/s	0	0 ms	Adjust Seam	Feeder Speed

Cancel Print Recover Print

What offers the new software update?

Updated and renewed User Interface

Custom profiles without the need of writing macros, every possibility parametrized.

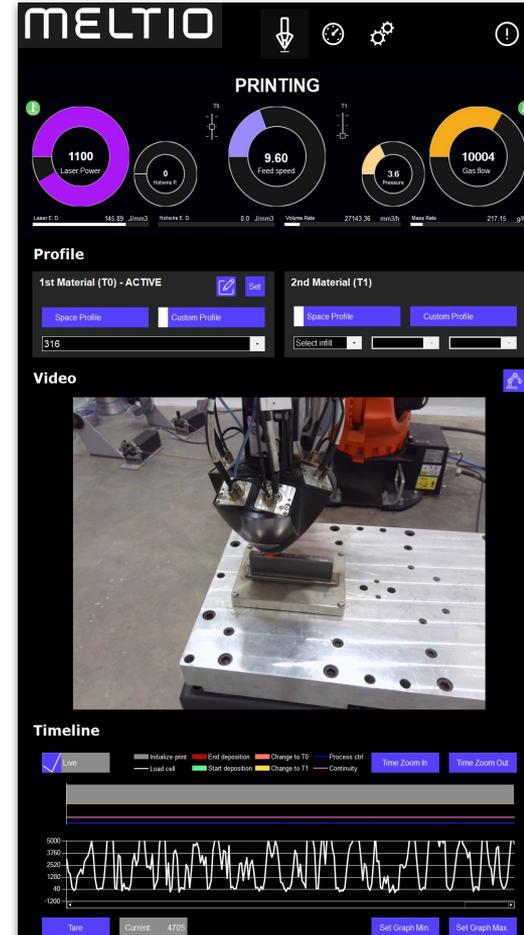
Live 3D model based on reading TCP positions from robot

Timeline for Sensors Analysis

4K Webcam Integration

Compatible with Welding Camera

Profiles for Meltio Materials and Meltio Space



Adjust Seam

Recommended extrusion and retraction values for single wire and dual wire.

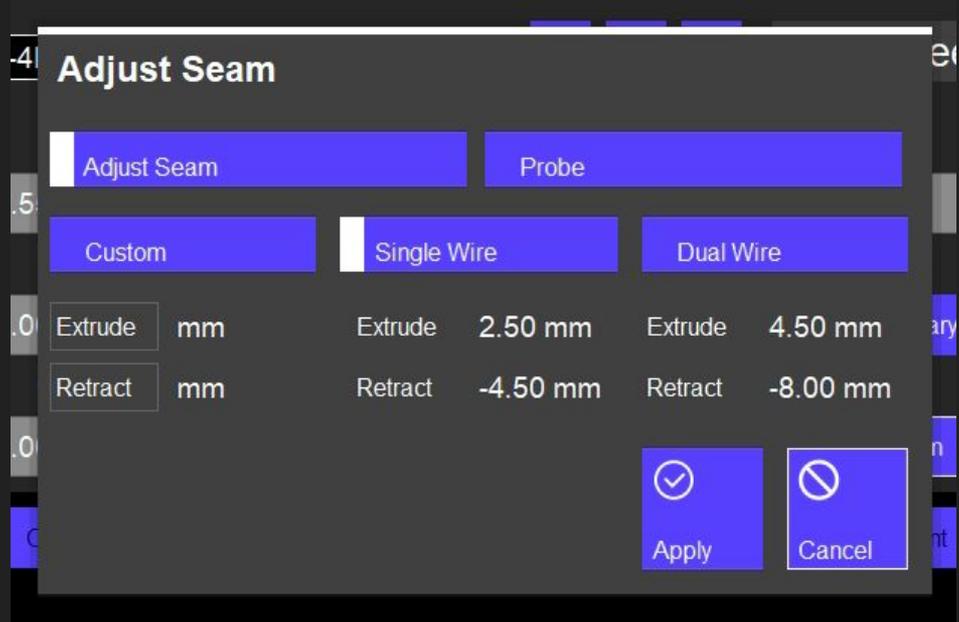
By default is set to :

Adjust Seam + Single Wire

Set to **Dual Wire** when combining different materials.

Probe is used for probing rather than a fixed extrusion distance.

Custom allow you to define any value within a safe range to adjust the seam as much as possible having always reference values for Single and Dual.



Webcam or Welding Camera Integration

Connect your USB Web Camera to the Meltio Engine Control Unit to follow the print through the Meltio Engine together with the Timeline.

Meltio Offers for purchase the 4K Vision Kit, including tripod, 15 meters USB extension cable and 4K Webcam, please request it through technical support.

We have as an alternative to the USB camera, the welding camera.

Video



Live 3D View

Connect your ABB Robot (WAN) and Meltio Engine to your local network.

Engine will read live TCP position and will show a 3D view as the program starts including colours according to the Load Cell values. Minimum (blue) and maximum (red) can be modified in configuration.

Currently only available for ABB, under development Kuka.

Regarding CNC controllers Haas, Fanuc and Siemens are in the development timeline too.



Profile

1st Material (T0)

Space Profile Custom Profile

Select infill

2nd Material (T1) - ACTIVE

Space Profile Custom Profile

mild steel test

Viewer

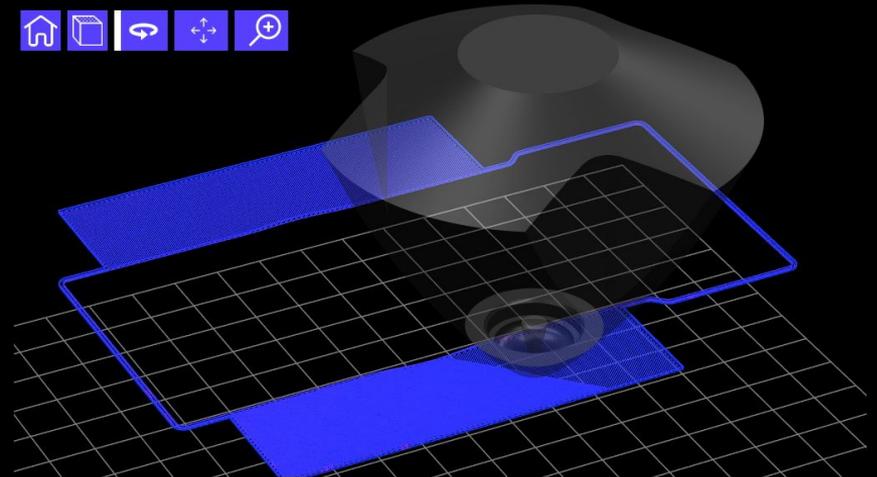


ABB Robot: 4600-107111 not connected
Not running

Reset 3D view at Initialize Print